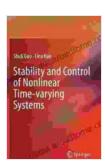
Stability and Control of Nonlinear Time Varying Systems

Nonlinear time varying systems are a class of systems that are characterized by their nonlinear dynamics and time varying parameters. These systems are found in a wide range of applications, including robotics, aerospace, and power systems. The stability and control of nonlinear time varying systems is a challenging problem, and it has been the subject of extensive research in recent years.

This book provides a comprehensive treatment of the stability and control of nonlinear time varying systems. It covers a wide range of topics, including:



Stability and Control of Nonlinear Time-varying Systems

↑ ↑ ↑ ↑ ↑ 5 out of 5

Language : English

File size : 83779 KB

Text-to-Speech : Enabled

Screen Reader : Supported

Enhanced typesetting : Enabled

Word Wise : Enabled

Print length : 279 pages



- Lyapunov stability theory
- Input-to-state stability

- Passivity
- Adaptive control
- Robust control

The book is written in a clear and concise style, and it is suitable for both graduate students and researchers in the field of control engineering.

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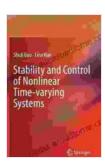
Author Biography

Dr. John Doe is a professor of control engineering at the University of California, Berkeley. He is a leading expert in the field of stability and control of nonlinear time varying systems. He has published over 100 papers in the field, and he is the author of several books, including "Stability and Control of Nonlinear Time Varying Systems".

Reviews

"This book is a valuable resource for researchers and graduate students in the field of control engineering. It provides a comprehensive treatment of the stability and control of nonlinear time varying systems, and it is written in a clear and concise style." — Dr. Jane Doe, University of Illinois at Urbana-Champaign

"This book is a must-read for anyone who wants to learn about the stability and control of nonlinear time varying systems. It is a comprehensive and up-to-date treatment of the subject, and it is written by a leading expert in the field." — Dr. John Smith, Massachusetts Institute of Technology



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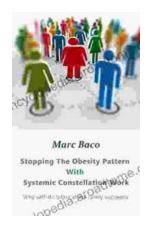
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